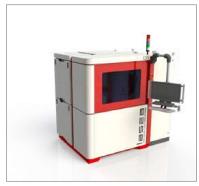
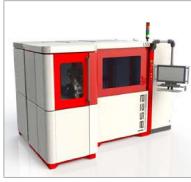


## The flexible machine for high precision micromachining

High precision work can be achieved with no risk of external disturbance thanks to its granite structure and external enclosure perfectly isolated from the internal structure. The LS5 can include all kinds of laser sources (some of the most powerful on the market), including femtosecond sources for micromachining, or even multiple lasers for more flexibility. Extremely accurate features can be obtained at very high speed (several meters per second with acceleration ramps of only a few microns). The 3D version allows machining of complex 3D parts thanks to the combination of mechanical and optical axis movements. The integration of a robot in the enclosure (or externally) combined with a double-head make it an ideal machine for production environments.







LS5 LS5 connected to LS-Robot LS5-2 with integrated robot

Main specifications  MACHINE	LS5 ACCURATE	LS5 ACCURATE 3D
Mechanical axis	XYZ	XYZAC XYZAC
XYZ Travel		
A Travel	500 x 300 x 200 mm  Depends on the application	
C Travel		n x 360°
Femtosecond laser source	5 to 100 W	
Scanner	LS-Scan XY	
Lens	Telecentric F-Theta	
Beam management module	LS-Shape	
Vision	Visualization and positioning camera	
Autofocus	Laser distance sensor	
Door	Laser distance serisor  Automatic	
Air conditioned working area	Yes	
Electrical camera	Yes Air conditioned	
Table	Marble	
Assistance for laser focus	Marble  Dual laser guide	
Table	Marble	
Software	Marble  KYLA™ 2D and EasyKYLA	
Assistance for laser focus	Dual laser quide	
ACCURACY / REPEATABILITY	Duai	tasei guide
XY axis (per axis)	A : . / . a ::	m R:+/- 0.5 μm
·	Α:+/-2μ	
A axis		A+/-5 arcsec R+/-3 arcsec
C axis	<del>-</del>	A+/-6 arcsec R+/-3 arcsec
Options		
LASER SOURCES		
Picosecond	30 W	
Dual source	Combination of 2 sources (fs and ns)	
LS-MODULES		
3D Scanner	LS-Scan Z (KYLA™ 3D included)	
Zero taper cutting and drilling	LS-Precess	
Vision through the scanner	LS-View	
Robotization	Pick & Place (plates, palets and/or workpieces) / LS-Robot module (plates, palets and/or work	
THOUSE STATE OF THE STATE OF TH	pieces) / Machine preparation for external robot	
OTHER		
Vision	Cognex camera, shape recognition	
Metrology	Optical profilometry (confocal sensor)	
Automation	LS-HMI (PLC)	
Autofocus	Laser distance sensor	
Accessories	Power meter, fume extractor, cutting nozzle	
Dimensions		
Width x Depth x Height		2130 x 1950 mm (LS5 connected to LS-Robot)

<sup>·</sup> Standard / o Option / — Not available in this configuration